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Optimal Control Systems; Nonlinear Systems; Advances in Control Systems; About The Author. I. J. Nagrath is the Adjunct Professor and former Deputy Director, BITS, Pilani. He has authored several leading books on engineering such as Modern Power System Analysis, Robotics and Control, Analog Computation and Simulation, and Basic Electrical Engineering.

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Control loops must have negative feedback. In Figure 3.1, if the sign of the summing junction is reversed from “–” to “+,” instability results. Many people have had the experience of reversing the leads of a tachometer, thermistor, or voltage sensor; the system runs away because positive feedback causes the correction signal generated from the loop to move the plant in the wrong ...

Summing Junction - an overview | ScienceDirect Topics

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